■ Features

•13 kinds of various operation modes: Revolution, speed, frequency, absolute ratio, passing time, error ratio, cycle, density, passing speed, error, time width, length measurement, time difference, interval, multiplication (MP5M Series have 11 operation modes)

•Various output function: Relay output, NPN/PNP open collector output, low speed serial output, BCD output,

PV transmission, RS485 communication output

Various functions :

Prescale function, data monitoring function, hysteresis function, peak value monitoring function, monitoring delay function, auto zero time setting function, lock setting function, display period delay function

- Max. display range : −19999 to 99999 (MP5M : 0 to 99999)
- ●Various display units: rpm, rps, Hz, kHz, sec, min, m, mm, mm/s, m/s, m/min, m/h, ℓ /s, ℓ /min, ℓ /h, %, counts, etc.
- •Selectable voltage input (PNP) or no voltage input (NPN)
- •50kHz high speed response

Ordering information





Main output (Comparative value output) Sub output (Display value output) S type N Indicator N Indicator Χ NPN open collector quintuple output Y type 2 PNP open collector quintuple output 3 Indicator BCD Dynamic Indicator 4 PV transmission output (DC4-20mA) 5 Indicator RS485 communication output Indicator Χ Output Five relay(HH, H, GO, L, LL) Triple relay(H, GO, L) Χ NPN open collector quintuple output BCD Dynamic 3 PNP open collector quintuple output BCD Dynamic W type NPN open collector quintuple output PV transmission output (DC4-20mA) PNP open collector quintuple output PV transmission output (DC4-20mA) NPN open collector quintuple output Low speed serial output PNP open collector quintuple output Low speed serial output NPN open collector quintuple output RS485 communication output RS485 communication output PNP open collector quintuple output Indicator Relay single(High-limit) output Χ M type + NPN open collector output Relay dual(High/Low-limit) output Χ + NPN open collector output Power supply 4 100-240VAC 50/60Hz DIN W48×H48mm DIN W72×H36mm Size W DIN W96×H48mm M DIN W72×H72mm Digit 5 99999(5 Digit) MP Pulse meter *PNP open collector output : Option

■Specifications(MP5S/MP5Y/MP5W Series)

Series		MP5S	MP5Y	MP5W		
Display m	ethod		gment LED display(Zero blanking t			
Character		W4 × H8mm		H13.8mm		
Max. indic			-19999 to 99999			
Power supply 100-240VAC 50/60Hz						
Allowable voltage		Alle	owable operation voltage : 90 to 11	0%		
Power con	sumption	Approx. 7.5VA(240VAC)	Approx. 3.5VA(240VAC)	Approx. 6VA(240VAC)		
	external sensor	Tippi oiii (10 (11 (2 10 (11 c)	12VDC ±10%, 80mA	Inprom o (II (210 (III))		
		• Soild-state i	input: Max. 50kHz(Pulse width: Ea	ach over 10us)		
Input freq	uency		t: Max. 45Hz(Pulse width: Over 1			
Input leve	I	[No-voltage input] Impeda	-24VDC, Low : 0-1.0VDC, Input im ance at short-circuit : Max. 300Ω, ance at open-circuit : Min. 100kΩ			
Measuring	range	Mode F1, F2, F7, F8, IMode F4, F5, F6 : 0.0	F9, F10 : 0.0005Hz to 50kHz • M 1s to 3,200s • Mode F11, F12,	ode F3 : 0.02s to 3,200s F13 : 0 to 4 ×10 ⁹ Count		
Measuring (23 ±5℃)	accuracy	• Mode F1, • Mode F3,	F2, F7, F8, F9, F10 : F.S. ±0.05% F4, F5, F6 : F.S. ±0.01%	0 0		
Display pe	eriod	0.05 / 0.5 / 1 / 2	/ 4 / 8sec.(It is same with period o	of output update.)		
Operation	mode					
Prescale f	unction	Direct in	nput method $(0.0001 \times 10^{-9} \text{ to } 9.999)$	9×10 ⁹)		
Hysteresis		(Note1)	0 to 9999			
• Lock setting function • Auto-Zero time setting function • Time unit selection function • Peak value monitoring function • Memory protection function (Mode F13 applied only) • Lock setting function • Monitoring delay function • Auto-zero time setting function • Current output range selection (Current output type • Comparative output function (HH, H, GO, L, LL) • Time unit selection function • Deviation memory function (F output mode applied only) • Peak value monitoring function • Remote/Local switching function (Note2) • Memory protection function (Mode F13 applied only)				Current output type only) I, H, GO, L, LL) Itput mode applied only) I (Communication output type only) Note2)		
Triple r Quintur NPN O	elay ole relay			250VAC 3A resistive load 3a		
.⊆ [(Quintt	oen collector		12-24VDC 30mA Max.	12-24VDC 20mA Max.		
tndtno Low spe	ynamic		NPN Open collector 12-24VDC 30mA Max.	NPN Open collector		
	ed serial output			12-24VDC 20mA Max.		
9 PV tran	smission		DC4-20mA Load 600Ω Max.	DC4-20mA Load 600Ω Max.		
RS485	communication		32 channels, Mutual directi	ion communication function		
Memory p	rotection	Non-vo	platile memory (Input: Min. 100,000			
Insulation	resistance		VDC megger) Between charge part			
Dielectric	stength		1minute (Between terminals of AC inals of AC power and measuring in			
Impulse no	oise stength	±2000VAC the square wave noi	se (pulse width : 1μ s) by the noise s	simulator, repeat frequency 60Hz		
Mechanical 0.75mm amplitude at frequency of 10 ~55Hz in each of X-Y-Z directions for 2 hour						
Vibration Malfunction 0.5mm amplitude at frequency of 10 to 55Hz in each of X, Y, Z directions for 10						
Mechanical 300m/s² (30G) in X, Y, Z directions for 3 times						
Shock Malfunction 100m/s² (10G) in X, Y, Z directions for 3 times						
Relay Malfunction —— Min. 10,000,000 times						
life cycle Mechanical Min. 100,000 times (250VAC 3A load current)						
Ambient temperature −10 to 50°C (at non-freezing status)						
	mperature		-20 to 60°C (at non-freezing status			
Ambient humidity 35 to 85%RH						
·						
Approval		A 100	(A 000		
Unit weigh	II	Approx. 130g	Approx. 135g	Approx. 230g		

** (Note1) The hysteresis setting range is changed by the setting position of decimal point. (Refer to M-25 for hysteresis function.)

Autonics M-6

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

> (J) Counter

(K) Timer

(L) Panel meter

> M) Facho/ Speed/ Pulse neter

(N) Display unit

(O) Sensor controller

(P) Switching power supply

(Q) Stepping motor & Driver & Controller

(R) Graphic/ Logic panel

(S) Field network device

(T) Production stoppage models & replacement

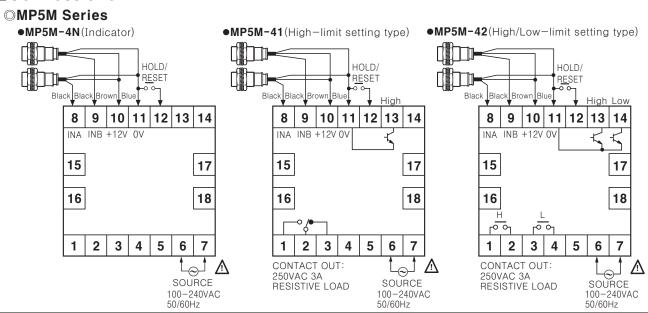
^{*(}Note2) Data bank switching function is in MP5W series only.

■Specifications(MP5M Series)

Model	MP5M-4N	MP5M-41	MP5M-42							
Model	Indicator	High-limit setting type	High/Low-limit setting type							
Display method	7 Segment LED	display(Zero blanking), Character si	ze: W4 X H8mm							
Max. indication	0.0001 to 99999									
Power supply		100-240VAC 50/60Hz								
Allowable operation voltage	Al	Allowable operation voltage: 90 to 110%								
Power consumption	Approx. 7.5VA(240VAC)	Approx. 8V	(A(240VAC)							
Power for external sensor		12VDC ±10%, 80mA								
Input frequency	• Contact i	ate input : Max. 50kHz(pulse width : input : Max. 45Hz(pulse width:over 1	11ms)							
Input level	[No-voltage input] Imped	-24VDC, Low: 0-1.0VDC, Input im lance at short-circuit: Max. 300Ω, lance at open-circuit: Min. 100kΩ								
Measuring range	• Mode F1, F2, F7, F8 : 0. • Mode F4, F5, F6 : 0.01s		0.02s to 3,200s 10, F11:0 to 4 ×10° Count							
Measuring accuracy (23 ±5°C)	• Mode F1, F2, F7, F8 : F.S. ±0.05% rdg ±1Digit • Mode F3, F4, F5, F6 : F.S. ±0.01% rdg ±1Digit									
Display period	0.05 / 0.5 / 1 / 2	0.05 / 0.5 / 1 / 2 / 4 / 8 sec. (It is same with period of output update.)								
Operation mode		Frequency(F1), Passing speed(F2), Once(F6), Absolute ratio(F7), Density F11) **Refer to M-19 to 3								
Prescale function	Direct input method(0.0001×10 ⁻⁹ to 9.9999×10 ⁹)									
Hysteresis		(Note1) 0 to	9999							
Other function	Lock setting function Auto-Zero time setting function Time unit selection function Peak value monitoring function Memory protection function (Mode F11 applied only)	Lock setting function Monitoring delay function Auto-Zero time setting function Time unit selection function Peak value monitoring function Memory protection function (Mode F11 applied only) High-limit output function(H)	Lock setting function Monitoring delay function Auto-Zero time setting function Time unit selection function Peak value monitoring function Memory protection function (Mode F11 applied only) Comparative output function (H, L) Output mode selection fuction (S, H, L, B, I, F) Deviation memory function (F output mode applied only)							
Main Relay output		250VAC 3A resistive load 1c	250VAC 3A resistive load 1a×2							
output NPN Open Collector		30VDC 100mA Max.	30VDC 100mA Max. ×2							
Memory protection	Non-v	rolatile memory (Input: Min. 100,000	times)							
Approval		CE : PU us	1							
Unit weight	Approx. 275g	Approx. 310g	Approx. 330g							

^{*}MP5S, MP5Y, MP5W have same function.

Connections



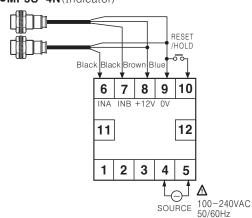
M-7 Autonics

^{*(}Note1) The hysteresis setting range is changed by the setting position of decimal point. (Refer to M-25 Page, hysteresis function.)

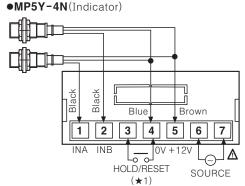
■ Connections

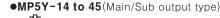
OMP5S Series

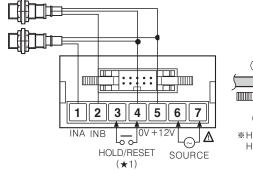
●MP5S-4N(Indicator)

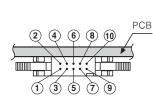


OMP5Y Series









★Hirose Connector:
HIF3BD-10PA-2.54DS

DC4-20mA

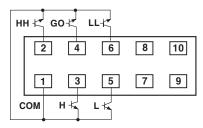
*****(★1)It is used for RESET terminal when an operation mode is F13. (Refer to M-19~22 for operation mode.)

Main output(Connector)

●MP5Y-41(NPN open collector output)

MAIN OUT

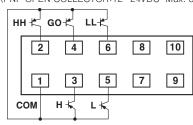
(NPN OPEN COLLECTOR:12-24VDC Max. 30mA)



●MP5Y-42(PNP open collector output)

MAIN OUT

(PNP OPEN COLLECTOR:12-24VDC Max. 30mA)

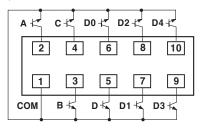


♦Sub output(Connector)

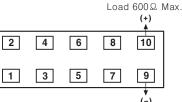
●MP5Y-43(BCD dynamic output)

BCD OUT

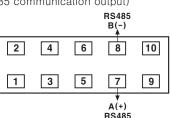
(NPN OPEN COLLECTOR:12-24VDC Max. 30mA)



●MP5Y-44(PV transmission output)



●MP5Y-45(RS485 communication output)



*Main output type & sub output type : Customizable

(A) Photo electric

(B) Fiber optic sensor

> (C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/

(H) Temp. controller

(I) SSR/ Power controller

> (J) Counter

(K) Timer

(L) Panel meter

(M) Tacho/ Speed/ Pulse meter

(N) Display

(O) Sensor controller

(P) Switching power supply

(Q) Stepping motor & Driver & Controller

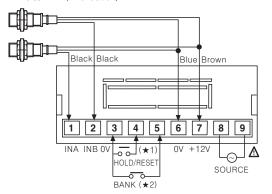
(R) Graphic/ Logic panel

(S) Field network device

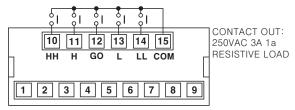
(T) Production stoppage models & replacement

OMP5W Series

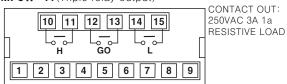




●MP5W-4A(Five relay output)

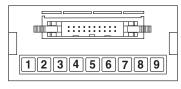


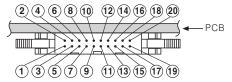
●MP5W-41 (Triple relay output)



- $(\star 1)$ It is used for RESET terminal when an operation mode is F13. (Refer to $M-19\sim22$)
- **※**(★2)Refer to M-25 for BANK function. *Main output type & sub output type: option

Main output+Sub output(Connector)

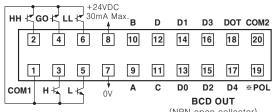




- *Hirose connector pin header model of the unit : HIF3BA-20PA-2.54DS
- *Contact Hirose Electric to purchase socket and wires of Hirose connector. [Socket: HIF3BA-20D-2.54R]
- ●MP5W-42/ MP5W-43(NPN/PNP open collector output + BCD output)

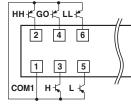


(NPN open collector :12-24VDC Max. 20mA)



MAIN OUT

(PNP open collector :12-24VDC Max. 20mA)



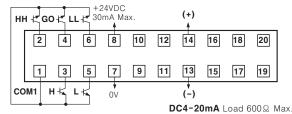
(NPN open collector) 12-24VDC Max. 20mA

*POL signal is on when it is - display value

●MP5W-44/ MP5W-45(NPN/PNP open collector output + PV transmission output(DC4-20mA) output)

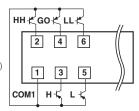






MAIN OUT

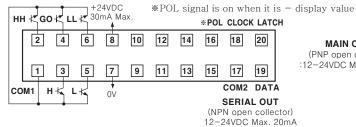
(PNP open collector :12-24VDC Max. 20mA)



●MP5W-46/ MP5W-47(NPN/PNP open collector output + Low speed serial output)

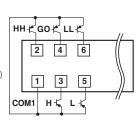






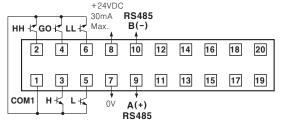
MAIN OUT

(PNP open collector :12-24VDC Max. 20mA)

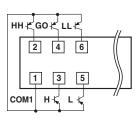


●MP5W-48/ MP5W-49(NPN/PNP open collector output + RS485 communication output)





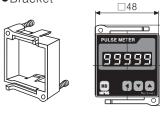
MAIN OUT (PNP open collector :12-24VDC Max. 20mA)



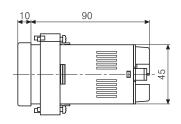
Dimensions

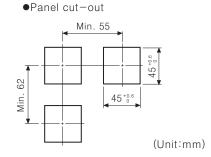


Bracket



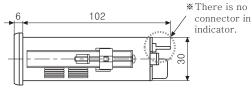
61

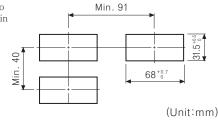




MP5Y Series





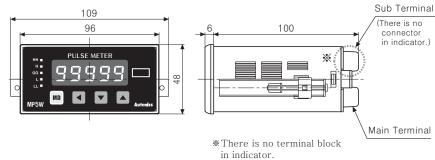


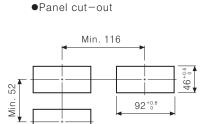
●Panel cut-out

**Hirose connector: HIF3BD-10PA-2.54DS

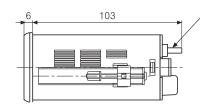
MP5W Series

[Terminal block type]





[Connector type]

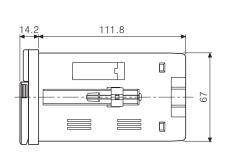


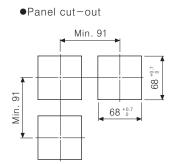
-*Hirose connector(There is no connector in indicator.) : HIF3BA-20PA-2.54DS

(Unit:mm)

●MP5M Series







(Unit:mm)

(A) Photo electric sensor

(B) Fiber optic sensor

> (C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

encoder (G)

Connector/ Socket

(H)
Temp.
controller

(I) SSR/

Power controller

(J) Counter

imer

(L) Panel meter

) icho/ ieed/ ilse

(N) Display unit

(O) Sensor controller

(P) Switching power supply

(Q) Stepping motor & Driver & Controller

(R) Graphic/ Logic panel

(S) Field network device

(T) Production stoppage models & replacement

Input specifications

OInput signal

- •Solid-state input
 - Input frequency: 50kHz Max.

Standard duty ratio of input signal is 1:1, ON/OFF pulse width should be over 10μ s.

- Input voltage level : High \rightarrow 4.5-24VDC, Low \rightarrow 0-1.0VDC
- •Relay contact input
 - Input frequency: 45Hz Max.

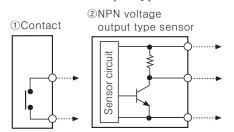
ON/OFF pulse width should be over 11ms.

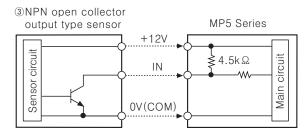
• Relay contact specification: Please use a relay contact that can carry the load current (Min. 12VDC 2mA).

Olnput type

MP5 has NPN input and PNP input and it is able to select in Parameter group 1.

•When it is NPN input type





Min. 10 μs

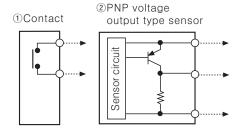
ON OFF

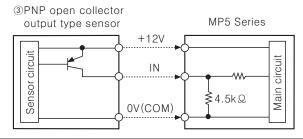
*T: 1cycle of input signal

High

Low

•When it is PNP input type





■Output specifications(MP5Y/ MP5W Series)

©BCD dynamic output (Negative logic)

●Output: Display value

ulletOutput signal:

BCD Data(A, B, C, D, DOT) \leftarrow A : Lowest bit

Dot: Highest bit

Digit Data(D0, D1, D2, D3, D4) ← D0 : Lowest digit

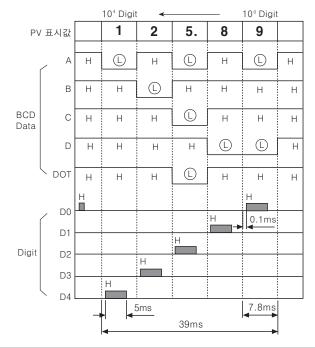
D4: Highest digit

**There is no DOT data output in MP5Y-43, therefore decimal point should be mark in first display plate.

●Output type: NPN open collector ●Rated load voltage: 12-24VDC

•Max. load current: 30mA(MP5Y)/20mA(MP5W)

Ex) When BCD dynamic output is 125.89



M-11 Autonics

©Low speed serial output (Negative logic)

Output: Display value

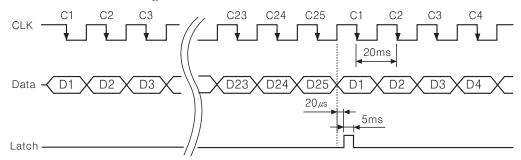
Output signal: Clock, Data, Latch

●Clock cycle: 50Hz ●Output CLK bit: 25 bit Output Data bit: 25 bit

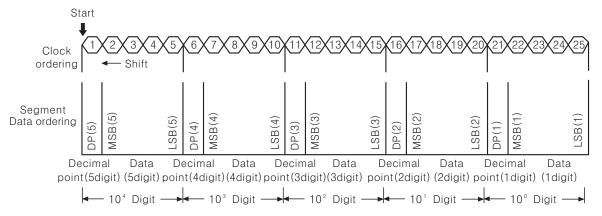
Output form: NPN open collector •Rated load voltage: 12-24VDC

•Max. load current: 30mA(MP5Y)/20mA(MP5W)

•Serial transmission time diagram



•Data output order when it is serial transmission



©PV transmission output (DC4-20mA)

- •Application: Transmit the measured value
- •Function: This function is to transmit DC4-20mA converted from measured display value between High limit output (FS-H) and Low limit (FS-L).
- •Range of High/Low limit output setting
 - High limit setting range (FS-H) From min. to max within range of measurement

• Low limit setting range(FS-L)

From min. to max within range of measurement $(FS-H \ge FS-L + 1 \text{ digit})$

•Load resistance : Max. 600Ω

•Resolution: 8000 division

©RS485 communication output

•Address: 0 to 99 address

•Transmission speed(Baud rate): 2400/4800/9600 bps

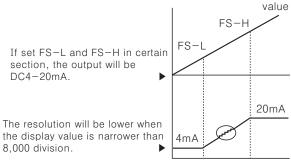
•Transmission code: ASCII

●Parity Bit: No ●Data Bit: 8 Bit •Stop Bit: 1 Bit

•Communication items

MP5W ← PC: Comparative value of each bank data, prescale value and peak value, RESET control MP5W → PC: Comparative value of each bank data, prescale value and peak value, display value

※Refer to M−26 for communication data.



(A) Photo electric sensor

Fiber optic sensor

> Door/Area sensor

Proximity sensor

Pressure sensor

Rotary encoder

(G) Connector/ Socket

Temp controller

SSR/ controller

> (J) Counter

Timer

(∟) Panel meter

Display

controller

Display

(P) Switching supply

Stepping motor & Driver & Controlle

(R) Graphic/ Logic panel

Field device

Production stoppage models & replacement

■ Parameter group chart for operation mode

- ●Parameter display are different according to each operation mode, refer to "■Parameter" part.
- \bullet " \bullet ": When select the operation mode, the parameter will be displayed.
 - "X": When select the operation mode, the parameter will not be displayed.
- \bullet " \bigcirc ": It is only able to set ${}_{n}P_{n}h.F$ or $P_{n}P.h.F$ for $I_{n} b$ sensor type in F11, F12, F13 of operation mode.

Parameter display		F1	F2	F3	F4	F5	F6	F7	F8	F9	F10	F11	F12	F13
	PSŁ.hh	•	0	•	0	•	•	•	0	•	•	•	•	•
	PSŁ. h	•	•	•	•	•	•	•	•	•	•	•	•	•
Parameter	PSŁ. L	•	•	•	•	•	0	•	•	•	•	•	•	•
group 0	PSŁ.LL	•	•	•	0	•	•	•	•	•	•	•	•	•
group 0	h.PEU	•	•	•	•	•	•	•	•	•	•	•	•	Х
	L.PEY	•	•	•	•	•	•	•	•	•	•	•	•	Х
	ñodE	•	•	•	•	•	•	•	•	•	•	•	•	•
	in-A	•	•	•	•	•	•	•	•	•	•	•	•	•
	In-b	Х	•	Х	Х	Х	•	•	•	•	•	0	0	0
	out-t	•	•	•	•	•	•	•	•	•	•	•	•	Х
Parameter	h45	•	Х	Х	Х	Х	Х	•	•	•	•	Х	Х	Х
group 1	GuAr.d ←→ F.dEFY	•	•	•	•	•	•	•	•	•	•	•	•	Х
	GuAr.d ←→ StAr.t	•	•	•	•	•	•	•	•	•	•	•	•	Х
	Auto.A	•	Х	Х	•	Х	Х	•	•	•	•	Х	Х	Х
	Auto.b	Х	Х	X	Х	X	Х	•	•	•	•	Χ	Х	Х
	ñEño	Х	X	Х	X	X	Х	X	Х	Х	Х	Х	Х	•
	P.bAnY	•	•	•	•	•	•	•	•	•	•	•	•	•
	dot	•	•	Х	Х	X	Х	•	•	•	•	•	•	•
	t.unt	Х	Х	•	•	•	•	Х	Х	Х	X	Х	Х	Х
	PSŁ.hh	•	•	•	•	•	•	•	•	•	•	•	•	•
	PSŁ. h	•	•	•	•	•	•	•	•	•	•	•	•	•
	PSŁ. L	•	•	•	•	•	•	•	•	•	•	•	•	•
Parameter group 2	PSŁ.LL	•	•	•	•	•	•	•	•	•	•	•	•	•
9.000	PSC.R.H	•	•	X	•	Х	Х	•	•	•	•	•	•	•
	PSC.R.Y	•	•	Х	•	Х	Х	•	•	•	•	•	•	•
	PSC.b.H	Χ	Х	Х	Х	Х	Х	•	•	•	•	Х	Х	Х
	PSC.6.9	Χ	Х	Х	Х	Х	Х	•	•	•	•	Х	Х	Х
	di S.P.E	•	Х	X	Х	X	Х	•	•	•	•	Χ	Х	Х
	F5-h When it is PV transmission output, it operates in all mode.													
F5-L When it is PV transmission output, it operate						erates	ın all n	node.						
Parameter	Addr													
group 3	6PS		Wh	nen it is	s RS48	5 com	munica	ation o	utput,	it oper	ates in	all mo	de.	
	rEñot													
	LoC	•	0	0	•	0	•	0	0	0	•	•	•	•

■ Operation mode by each series

Operation Series nam	mode	Frequency rotation speed	Passing speed	Cycle	Passing time		Time difference	Absolute ratio	Error ratio	Density	Error	Length measurement	Interval	Multiplication
MP5S/MP5Y	/MP5W	F1	F2	F3	F4	F5	F6	F7	F8	F9	F10	F11	F12	F13
MP5N	1	F1	F2	F3	F4	F5	F6	F7	Х	F8	Х	F9	F10	F11

F-13 Autonics

■Parameter group chart for model

- ●The parameter has different mode according to each model, therefore refer to "■Parameter group chart of operation mode" and "■Parameter".
- • When selecting the operation mode, the parameter will be displayed.
 - X: When selecting the operation mode, the parameter will not be displayed.

Pá	Model	MP5S-4N MP5Y-4N MP5W-4N MP5M-4N		MP5Y-43	MP5Y-44	MP5Y-45	MP5W-41	MP5W-4A MP5W-42 MP5W-43	MDEW-45		MP5W-48 MP5W-49	MP5M-41	MP5M-42
0	PSŁ.hh	X	•	Х	Х	X	Х	•	•	•	•	Х	X
group	PSŁ. h	Х	•	Х	Х	Х	•	•	•	0	•	Х	Х
r gr	PSŁ. L	Х	•	Х	Х	Х	•	•	•	•	•	Х	Х
Parameter	PSŁ.LL	Х	•	Х	Х	Х	Х	•	•	•	•	Х	Х
am	h.PEY	0	•	•	•	•	•	•	•	0	•	•	•
Ра	L.PEY	•	•	•	•	•	•	•	0	•	•	•	•
П	ñodE	•	0	0	0	0	0	0	0	0	0	0	
	In-A	0	0	0	0	0	0	0	•	0	0	0	0
1	In-b	•	•	•	•	•	•	•	•	•	•	•	•
group 1	out-t	Х	•	X	X	Х	•	0	•	•	0	X	•
	h45	Х	0	X	Х	Х	•	0	•	•	•	•	0
ete	GuAr.d ↔ F.dEFY	X	•	Х	Х	Х	•	•	•	0	•	Х	•
arameter	GuAr.d ↔ StAr.t	Х	•	Х	Х	Х	•	•	•	•	•	Х	0
Ра	Auto,A	•	•	•	•	•	•	•	•	•	•	•	•
	Auto.b	•	•	•	•	•	•	•	•	•	•	•	•
	ñEño	•	•	•	0	•	•	•	•	0	•	•	•
	P.bAnY	0	Х	Х	Х	Х	•	0	•	0	0	Х	X
	dot	•	•	•	•	•	•	•	•	•	•	•	•
	Ł.unt	•	•	•	•	•	•	•	•	•	•	•	•
2	PSŁ.hh	Х	•	Х	Х	Х	Х	•	•	•	•	Х	Х
group	PSŁ. h	Х	•	Х	Х	Х	•	•	•	•	•	Х	Х
gr	PSŁ. L	Х	•	Х	Х	Х	•	•	•	•	•	Х	Х
Parameter	PSŁ.LL	X	•	X	X	X	X	•		•	•	X	X
am	PSC.R.H	•	•	•	•	•	•	•		•	•	•	•
Раі	PSC.R.Y	•	•	•	•	•	•	•	•	•	•	•	•
	PSC.b.H	•	•	•	•	•	•	•	•	•	•	•	•
	PSC.6.Y	•	•	•	•	•	•	•	•	•	•	•	•
	d1 5 P.E	•	•	•	•	•	•	•	•	•	•	•	•
3	FS-h	X	X	Х	•	X	Х	Х	•	X	Х	X	Х
dno	FS-L	Х	X	Х	0	Х	Χ	Х	•	Х	Х	Χ	Х
r gr	Addr	Х	X	Х	Х	•	Х	Х	Χ	X	•	Х	Х
ete	6PS	Х	Х	Х	Х	•	Х	Х	Χ	X	•	Х	Х
Parameter group	rEñot	X	X	Х	Χ	•	Х	Х	Χ	Х	•	Х	Х
Ра	LoC	•	•	•	•	•	•	•	•	•	•	•	•

^{*} Data bank (P.bAnt) setting is available in only MP5W-4N.

■ Monitoring delay operation function chart by each output mode

out-t	SEArd	out-h	out-L	out-b	out-1	out-f
Comparative output limit function	•	Х	X	•	X	•
Starting correction timer function	•	0	•	•	•	•

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area

(D) Proximity sensor

(E) Pressure

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

(J) Counter

(K) Timer

Panel meter
(M)

M) acho/ peed/ ulse neter

(N) Display unit

(O) Sensor controller

(P) Switching power supply

(Q) Stepping motor & Driver & Controller

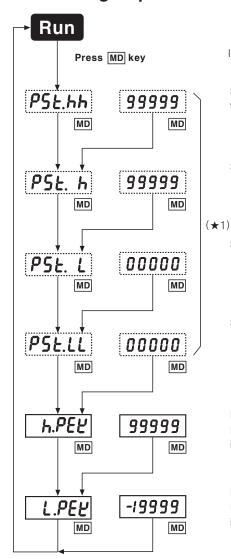
Graphic/ Logic panel

(S) Field network device

(T) Production stoppage models & replacement

■ Parameter

Parameter group 0



If **MD** key is pressed in **RUN** mode, it will advance to Parameter group 0.

Set HH comparative value. Refer to the "Setting range of comparative value by operation mode" for a setting range.

(◀: Shift the setting digit ▼, ▲: Change the setting value)

Set H comparative value.

- (**■** : Shift the setting digit
- , 🛕 : Change the setting value)

Set L comparative value.

- (: Shift the setting digit
- ▼, ▲: Change the setting value)

Set L comparative value.

- (<a>■ : Shift the setting digit
- ▼, ▲: Change the setting value)

•Setting range of comparative value by operation mode

Series	Operation mode	Setting range
MP5S	F1, F2, F7, F9, F11, F12, F13	0 to 99999
MP5Y MP5W	F3, F4, F5, F6	0 to Setting time range
IVIPSW	F8, F10	-19999 to 99999
MP5M	F1, F2, F7, F8, F9, F10, F11	0 to 99999
	F3, F4, F5, F6	0 to Setting time range

*The setting range is changed by setting position of decimal point.

Display High Peak value among measuring values.

If \(\big \) key is pressed for 2 sec., The High Peak value will be reset and it displays a current measuring value

Display Low Peak value among measuring values.

- If \P key is pressed for 2 sec., The Low Peak value will be reset and
- it displays a current measuring value

*If MD key is pressed in RUN mode, it will advance to Parameter group 0.

*When advance to Parameter group 0, parameter and set data value is flashed as 1 sec. cycle.

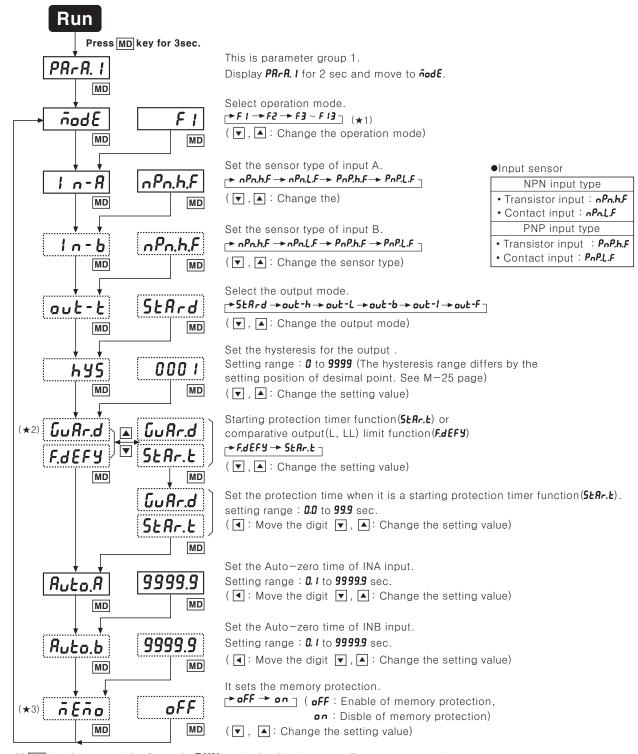
- $*(\star 1)$ The parameter shown in dotted line is displayed only for comparative value setting type.
 - If F mode is selected among output modes, it is to set H and L deviation only, therefore [PSŁ.hh] and [PSŁ.LL] parameter will not appear.

**After setting value in each parameter is changed, data will be saved by press MD key for 2sec. and return to RUN mode, but if any keys are untouched for 60sec. while changing data, it will return to RUN mode with previous set value.

• If it is not comparing value setting type, [h.PEL] will appear when advance to parameter group 0.

M-15 Autonics

Parameter group 1



- #If $\underline{\mathbf{MD}}$ key is pressed for 3 sec. in \mathbf{RUN} mode, it will advance to Parameter group 1.
- ₩When advance to Parameter group 1, parameter and set data value flash as 1 sec. cycle.
- *The parameter shown in dotted line is not displayed by operating mode.

(Refer to M-13, " \blacksquare Parameter group chart for operation mode".)

- (*1)MP5M type is able to select from F1 to F11.
- ※ (★2) The parameter is displayed in case of comparative value setting type only.

 (Except for indicator and MP5M-41)
- ★ (★3) The selecting function of memory protection is displayed when the mode is F13 (Multiplication mode).

 (But, F11 mode for MP5M)
- *After changing setting value in each Parameter, data will be saved by press MD key for 2sec. and return to RUN mode, but if any keys are untouched for 60sec. while changing data, it will return to RUN mode with previous set value.

Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

(J) Counter

(K) Timer

(L) Panel meter

(M) Tacho/ Speed/ Pulse meter

(N) Display

(O) Sensor controller

(P) Switching power supply

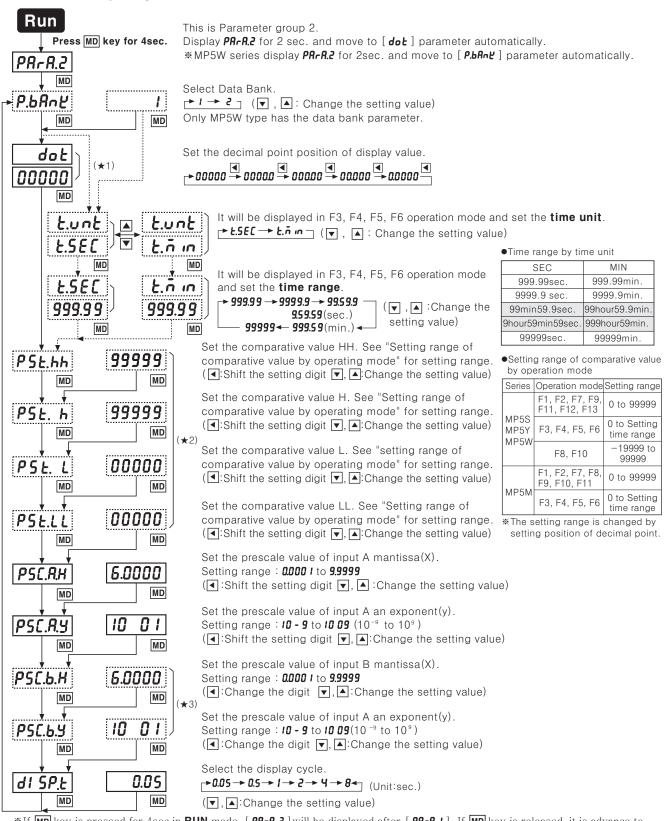
(Q) Stepping motor & Driver & Controller

(R) Graphic/ Logic panel

(S) Field network device

(T) Production stoppage models & replacement

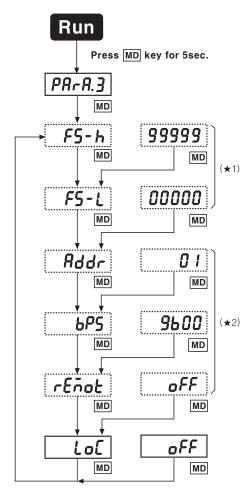
Parameter group 2



- *If MD key is pressed for 4sec.in RUN mode, [PArA.2] will be displayed after [PArA.1]. If MD key is released, it is advance to Parameter group 2.
- ₩When advance to Parameter group 2, parameter and set data value is flashed as 1 sec cycle.
- **※**(★1)It will be displayed only in F3, F4, F5, F6 modes.
- ※ (★2) If F mode is selected among output modes, it is set H and L deviation only, therefore [PSŁ.hh] and [PSŁ.LL] parameter will not appear.
- **※**(★3)It will be displayed only in F7, F8, F9, F10 modes. But in case of MP5M type, it is displayed only in F7, F8 modes.
- **After setting value in each parameter is changed, data will be saved by press MD key for 2sec. and return to RUN mode, but if any key is untouched for 60sec. while changing data, it will return to RUN move with previous set value.

M-17 Autonics

Parameter group 3



This is Parameter group 3.

Display PArA.3 for 2 sec. and move to [F5-h] parameter automatically.

Set the High-limit value of PV transmission output.

See "Setting range of comparative value by operating mode" for setting range

(◀:Shift the setting digit ▼, ▲:Change the setting value)

Set the Low-limit value of PV transmission output.

(◀:Shift the setting digit ▼, ▲:Change the setting value)

•Setting range of comparative value

by operation mode

Series	Operation mode	Setting range
	F1, F2, F7, F9, F11, F12, F13	0 to 99999
MP5S MP5Y MP5W	F3, F4, F5, F6	0 to Setting time range
IVII OVV	F8, F10	-19999 to 99999
MP5M	F1, F2, F7, F8, F9, F10, F11	0 to 99999
IVIPSIVI	F3, F4, F5, F6	0 to Setting time range

*The setting range is changed by setting position of decimal point.

Set the communication Address setting range : 0 1 to 99

(Shift the setting digit

▼, ▲: Change the setting value)

Set the communication Speed.

→ 9600 → 4800 → 2400 ¬

(**■**:Shift the setting digit

▼, ▲: Change the setting value)

Select the Remote and the Local.

ightharpoonup off: Local, on: Remote)

(▼, ▲: Change the setting value)

Enable to lock the key for each parameter group

→ oFF → LoC. O → LoC. I -- Lo[.3 ← Lo[.2 ←

LoC. 0: P0 to 3 Lock (▼, ▲:Change the setting value)

LoC. 1: P1 to 3 Lock **LoC.2**: P2 to 3 Lock L **LoC.3**: P3 Lock only

oFF : Lock cancel

- *If [MD] key is pressed for 5sec. in RUN mode, [PArA.3] will be displayed after [PArA.1] and [PArA.2].
- If **MD** key is released, it is advance to Parameter group 3.
- *When it advances into Parameter group 3, parameter and data value is flashed as 1 sec. cycle.
- **※** (★1) The parameter is displayed in case of PV transmission output type only.
- * (★2) The parameter is displayed in case of RS485 transmission output type only. When Remote [rɛñot] is selected, it is not able to operate front keys.
- *After setting value in each parameter is changed, data will be saved by press MD key for 2sec and return to RUN mode, but if any key is untouched for 60sec while changing data, it will return to **RUN** move with previous set value.

Factory defaits

Parameter 1 group

Mode	Setting value
ñodE	F !
ln-A	nPn.h.F
out-t	SEArd
hY5	000 1
5∪Ar.d	F.dEFY
RutoA	99999
ñEño	oFF

Parameter 2 group

Mode	Setting value
<i>የ</i> .ሁጸ _^ ይ	1
dot	00000
PSŁ.hh	99999
PSŁ. h	99999
PSŁ. L	00000
PSELL	00000
PSCRH	<i>6.000</i>
PSCRY	10 01
di SP.E	0.05

Parameter 3 group

Mode	Setting value
F5-h	99999
FS-L	00000
Addr	01
6 PS	9600
rEñot	oFF
LoC	oFF
	•

*Setting specification may not be displayed because of operation mode or output specification.

Photo sensor

(B) sensor

Door/Area sensor

Proximity sensor

Pressure sensor

Rotary encoder

(G) Connector/ Socket

(H) Temp.

(I) SSR/ Power controller

Counter

(K)

(L) meter

unit

Sensor

Switching power supply

Stepping motor & Driver & Controlle

(R) Graphic/ Logic panel

(S) network device

Production stoppage models & replacement

Operation mode

- •Select operation mode from **nodE** (mode) of Parameter group 1.
- There are 13 kinds of operation mode in MP5S, MP5Y, MP5W.

There are 11 kinds of operation mode in MP5M series.

●Mode F1 (Frequency/Number of revolution/Speed)

This mode is to display calculated frequency or number of revolution or speed by measuring frequency of Input A.

1) Frequency (Hz) = $f \times \alpha$ [$\alpha = 1$ (sec.)]

2) Number of revolution (rpm)

= f
$$\times$$
 a [α = 60(sec.)]

Several targets
$$\alpha = 60 \times \frac{1}{N}$$

3)Speed(m/min) = f
$$\times$$
 α [α = 60 \times L(m)]

Several targets
$$\alpha = 60 \times L \times \frac{1}{N}$$

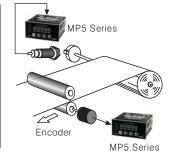
*L = The length of conveyor moved for 1 pulse cycle[m]

N: Number of sensing target (Number of pulse per revolution)

 α : Prescale value

•Display value and display unit

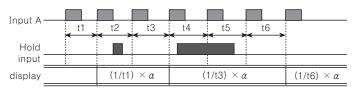
Display value	Display unit	α (Prescale value)		
Fraguanay	Hz	1		
Frequency	kHz	0.001		
Number of	RPS	1		
revolution	rpm	60		
	mm / sec.	1,000L		
	cm / sec.	100L		
Speed	m / sec.	L		
	m / min.	60L		
	km / hour	3.6L		



MP5 Series

*Display unit of default : rpm

Time chart



Mode F2(Passing speed)

Display the passing speed between ON of input A and ON of input B.

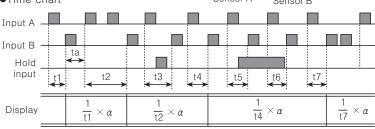
Passing speed(V) =
$$f \times \alpha [\alpha = L(m)]$$

- **%**f: This is reciprocal number of the time between ON of input A and ON of input B.
- L: The distance between input A and input B[m]
- α : Prescale value

•Display value and display unit

Display value	Display unit	α (Prescale value)
	mm / sec.	1,000L
	cm / sec.	100L
Passing speed	m / sec.	L
speed	m / min.	60L
	km / hour	3.6L

*Display unit of factory default: m/sec. Sensor A Time chart



ta: It requires min. 20ms for return time

●Mode F3(Cycle)

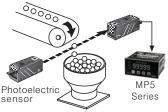
Display the time from when input A is ON to the next ON.

Cvcle(T) = t

**t: Measurement time [sec.]

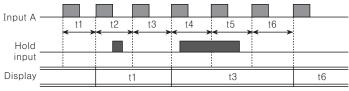
Display value and display unit

Display value	Display unit	
	SEC	MIN
	999.99sec.	999.99min.
	9999.9sec.	9999.9min.
Cycle	99min. 59.9sec.	99hour 59.9min.
	9hour 59min. 59sec.	999hour 59min.
	99999sec.	99999min.



Set the display unit at the **Lunt**(Time unit) of Parameter 2. *Display unit of factory default: 999.99sec.

Time chart



*t1 to t6 should be over min. 20ms for measuring.

[★] is not displayed in MP5M-4N, MP5M-41, MP5M-42.

●Mode F4(Passing time)

It displays the pass time of certain distance to measure the time between ON and the next ON of Input A.

Passing time(sec) = $t \times a$

 $\mathbf{\alpha} = \frac{L(m)}{\text{Moving distance within 1pulse cycle[m]}}$

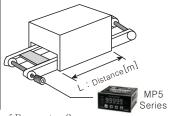
%t : Measurement time[sec .]
L : Certain distance[m]

* α: Presale value

★ is not displayed in MP5M-4N, MP5M-41, MP5M-42.

Display value and display unit

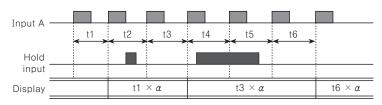
Display unit	
SEC	MIN
999.99sec.	999.99min.
9999.9sec.	9999.9min.
99min. 59.9sec.	99hour 59.9min.
9hour 59min. 59sec.	999hour 59min.
99999sec.	99999min.
	SEC 999.99sec. 9999.9sec. 99min. 59.9sec. 9hour 59min. 59sec.



\$ Set the display unit at the $\verb"b.unk"$ (Time unit) of Parameter 2.

*Display unit of factory default: 999.99sec.

Time chart



■Mode F5(Time width)

It displays the ON time of input A.

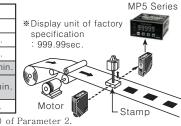
Time width(T) = t

*t: ON measurement time of input A[sec.]

★ is not displayed in MP5M-4N,

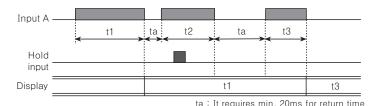
ullet Display value and display unit

Display value	Display unit	
	SEC	MIN
	999.99sec.	999.99min.
	9999.9sec.	9999.9min.
Time width	99min. 59.9sec.	99hour 59.9min.
	9hour 59min. 59sec.	999hour 59min.
	99999sec.	99999min.
W.O	the state of	1 (T): :-) (



**Set the display unit at the <code>t.unt</code>(Time unit) of Parameter 2. **Display unit of factory default : 999.99sec.

Time chart



●Mode F6(Time difference)

MP5M-41, MP5M-42.

It displays the time from input A is ON to input B is ON.

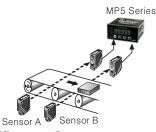
Time difference(T) = $t(Ta \sim Tb)$

★ is not displayed in MP5M-4N,

MP5M-41, MP5M-42.

•Display value and display unit

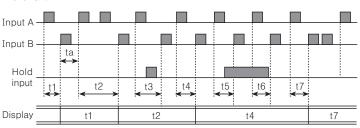
Display value	Displa	y unit
	SEC	MIN
	999.99sec.	999.99min.
	9999.9sec.	9999.9min.
Time interval	99min. 59.9sec.	99hour 59.9min.
	9hour 59min. 59sec.	999hour 59min.
	99999sec.	99999min.



 \divideontimes Set the display unit at the $\pmb{k.unk}$ (Time unit) of Parameter 2.

*Display unit of factory default: 999.99sec.

•Time chart



ta: It requires min. 20ms for return time

Autonics M-20

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

> (J) Counter

(K) Timer

(L) Panel meter

(M) Facho/ Speed/ Pulse

(N) Display unit

(O) Sensor controller

(P) Switching power supply

(Q) Stepping motor & Driver & Controller

(R) Graphic/ Logic panel

(S) Field network device

(T) Production stoppage models & replacement

● Mode F7 (Absolute ratio)

It displays how fast or late Input B comparing to Input A as well as speed or amount of Input, as a percentage.

Absolute ratio = (Input B / Input A) × 100%

Absolute ratio = $\frac{\text{Frequency of input B[Hz]} \times \mathbf{B} \alpha}{\text{Frequency of input A[Hz]} \times \mathbf{A} \alpha}$

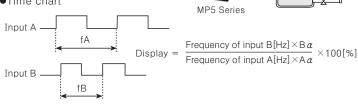
 $A \alpha$: Prescale for input A $B \alpha$: Prescale for input A

Display value and display unit

Display value	Display unit
Absolute ratio	%

× 100[%]

●Time chart



**Hold : Hold signal is ON, the display value will be held until Hold signal is OFF.

●Mode F8(Error ratio)

It displays how fast or late as a percentage(%) for input B against input A.

Error ratio=
$$\frac{Input B-Input A}{Input A} \times 100[\%]$$

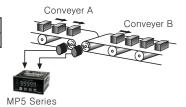
Error ratio=
$$\frac{(\text{Frequency of input B[Hz]} \times \text{B} \alpha)}{-(\text{Frequency of input A[Hz]} \times \text{A} \alpha)} \times 100[\%]$$
Frequency of input A[Hz] $\times \text{A} \alpha$

**Error ratio mode is not available in MP5M-4N, MP5M-41, MP5M-42 models.

•Display value and display unit

Display value	Display unit
Error ratio	%

** A α: Prescale for input A B α: Prescale for input B

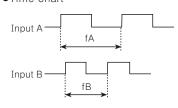


B Flow meter

A Flow meter

Liquid

Time chart



**Hold: Hold signal is ON, the display value will be held until Hold signal is OFF.

●Mode F9(Density)

It displays the density ratio of input B against total sum of input A and input B.

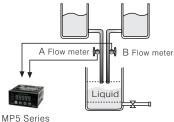
Density=
$$\frac{Input B}{Input A + Input B} \times 100[\%]$$

Density=
$$\frac{\text{Frequency of input B[Hz]} \times \text{B} \alpha}{\text{(Frequency of input A[Hz]} \times \text{A} \alpha)} \times 100[\%] + (\text{Frequency of input B[Hz]} \times \text{B} \alpha)$$

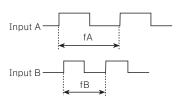
•Display value and display unit

Display value	Display unit	
Density	%	
*Aα: Prescale value of input A		

**A α :Prescale value of input A B α :Prescale value of input B



Time chart



*Hold: Hold signal is ON, the display value will be held until Hold signal

★F8 mode is applied to MP5M-4N, MP5M-41, MP5M-42 models. is OFF.

M-21 Autonics

●Mode F10(Error)

It displays the error between standard input A and comparing input B.

Error = Input B - Input A Error = (Frequency of input B[Hz] \times B α) - (Frequency of input A[Hz] \times A α)

 There is no error mode in MP5M−4N, MP5M-41, MP5M-42 models.

•Mode F11 (Length measurment)

It displays the number of input A pulse while input B is ON.

Length measurment = $P \times a$

※P: Number of input A pulse,

α: Prescale value

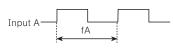
MP5M-41, MP5M-42 models.

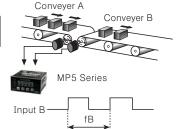
Display value and display unit

Display value	Display unit
Error	END User setting unit

*A α: Prescale value of input A B α: Prescale value of input B

Time chart



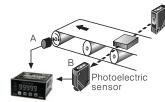


**Hold: Hold signal is ON, the display value will be held until Hold signal is OFF.

Display value and display unit

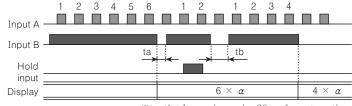
Display value	Display unit
	Quantity[EA]
Length	mm
measurement	cm
	m

*Factory default(Unit): Quantity[EA]



MP5 Series

Time chart



*ta, tb: It requires min. 20ms for return time

●Mode F12(Interval)

It displays the number of input A pulse from input B is ON to the time input B is ON next.

Interval = $P \times \alpha$

※P: Number of input A pulse,

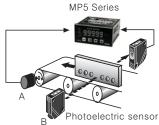
α: Prescale value

¥F10 mode is applied to MP5M−4N, MP5M-41, MP5M-42 models.

•Display value and display unit

Display value	Display unit
	Quantity[EA]
Interval	mm
IIItervai	cm
	m

*Factory default (Unit) : Quantity [EA]



●Time chart 2 2 3 4 3 Input A -Input B ta tb Hold input Display

*ta: It requires min. 20ms for return time

●Mode F13(Multiplication)

It displays the counting value against pulses of input A.

Multiplication = $P \times \alpha$

₩P: Pulse number of input A,

 α : Prescale value

*Max. counting speed: 50kcps (same with max. response frequency)

MP5M-41, MP5M-42 models.

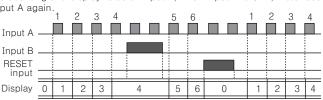
Display value and display unit

Display value	Display unit
Multiplication	Quantity[EA]

Operation and Time chart

(1) It counts the number of Input A pulse.

②Input B is an Enable/Disable input signal, when Input B is ON, meter stops the counting and display value of Input A, when Input B is OFF, meter counts Input A again.



* α =1 display value

(A) Photo electric sensor

(B) Fiber sensor

Door/Area

Proximity sensor

Pressure

Rotary encoder

(G) Connector/ Socket

Temp controller

SSR/ Power controller

(J) Counter

Timer

(∟) Panel meter

Display

Sensor controller

Switching supply

(Q) Stepping motor & Driver & Controlle

(R) Graphic/ Logic panel

MP5

Series

(S) Field network device

Production stoppage models & replacement

Output mode

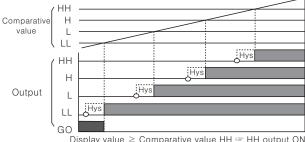
- Select output mode in out-t(output type) of Parameter group 1.
- •MP5 series are 6 kinds of output mode. There is no output mode in indicator type, MP5Y-43/44/45, MP5M-41 models. S(Standard) output mode, H(High) output mode, L(Low) output mode, B(Block) output mode, I(One shot)output mode, F(Deviation)output mode.
- •In order to set comparative value, B output mode should be LL<L<H<HH, other S, H, L, I output modes operate individually, regardless of value size of comparative setting value.

 (There is no GO, HH, LL, OUTPUT in MP5M-42)

Os(Standard) output mode[5£Ard] Comparative value HH L L LL HH GO L HHS Hys

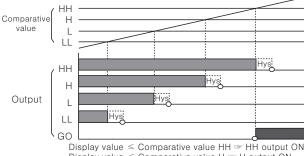
Display value ≥ Comparative value HH → HH output ON Display value ≥ Comparative value H → H output ON Display value ≤ Comparative value L → L output ON Display value ≤ Comparative value LL → LL output ON GO output: When there are no HH, H, L, LL output, it will be ON.

○H(High) output mode[ܩܙܠ-Һ]



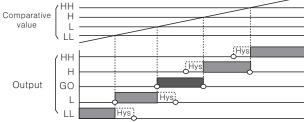
Display value ≥ Comparative value HH → HH output ON
Display value ≥ Comparative value H → H output ON
Display value ≥ Comparative value L → L output ON
Display value ≥ Comparative value LL → LL output ON
GO output: When there are no HH, H, L, LL output,
it will be ON.

○L(Low) output mode[out-L]

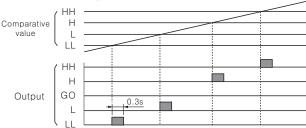


Display value ≤ Comparative value HH → HH output OI Display value ≤ Comparative value H → H output ON Display value ≤ Comparative value L → L output ON Display value ≤ Comparative value LL → LL output ON GO output: When there are no HH, H, L, LL output, it will be ON.

○B(Block) output mode[оы Е-ь]



OI(One Shot) output mode[out-!]



Display value \geq Comparative value HH $\mathscr P$ HH output ON Comparative value HH \Rightarrow Display value \geq Comparative value H \Rightarrow H output ON Comparative value H \Rightarrow Display value \geq Comparative value L \Rightarrow L output ON Comparative value L \Rightarrow Display value \geq Comparative value LL \Rightarrow LL output ON

- *There is no GO output in output mode I.
- **One Shot(■) output time has been fixed 0.3sec.
- *There is no Hysteresis in I(One shot) comparative output mode.

○F(Deflection) output mode[out-F]

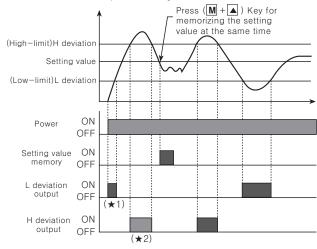
This function is to memorize the setting value and it outputs when exceed the deviation of H, L.

- Memorize the setting value : Memorize the current display value as the setting value with pressing(M + ▲) key is front.
- ●Display the setting value: Check the memorized the setting value by (▲) key. (Display the memorized setting value for pressing ▲ key continuously.)
- Deviation setting: Set H[P5L. h], L[P5L. L] deviation by setting value. (The set deviation will be memorized until set the next deviation again when power off.)
- •Deviation setting range : 0.0001 to 99999 (The setting range will be changed by decimal point setting parameter.

 If setting decimal point as 0000 0, the setting range will be

If setting decimal point as 0000.0, the setting range will be 0.1 to 9999.9.)

Operation: Display value ≤ L Comparative value ⇒
 L Comparative output ON,
 Display value ≥ H Comparative value ⇒
 H Comparative output ON



- ※ (★1) When selecting the comparative output limit function, Initial output will not be come.
- ★ (★2) The output on the above is on the assumption that the prior setting value of memory can be available.
- *There are no HH, GO, LL outputs in F output mode.
- *Even though, set the deviation as "O(Zero)", it will work as "deviation 1".

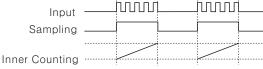
M-23 Autonics

■ Function

OSelection of display interval

It measures and displays reciprocal number of measuring time to detect target. Measuring accuracy may be dropped because the measuring time of interval is short, if the target is revolving with high speed.

It is able to change the display cycle in range of 0.05/0.5/1/2/4/8sec.) and displays the average value of measuring value then able to maintain measuring accuracy when revolving with high speed. In case of preset output type, the response can be delayed when the measuring time is long. Therefore, please adjust the measuring time properly.



*Select display sampling period in parameter 2.

OPrescale function

This prescale function allows to multiply the number of pulse or pulse length by a variable (X \times 10 $^{\rm y}$) then display specification of measurement.

It will display frequency or RPM from prescale value by measuring the input frequenc. For example, what is prescale value α when rpm is displayed?



* f: Input pulse (Frequency) per sec.

* α: Prescale value

※N: Pulse number per 1 revolution

•Prescale value ($\alpha = 15$) setting Set Prescale value (α) as (X) and (y) separately in **PSLRH**, **PSLRY**(**PSLb.H**, **PSLb.Y**) of Parameter group 2. Set Prescale ($\alpha = 15$) as (X):1.5000, (y):10¹ It is also able to get the same display value even though set as X=0.1500, y=10² X setting range: 0.0001 to 9.9999

X setting range : 0.0001 to 9.9999 Y setting range : 10⁻⁹ to 10⁹

Peak value monitoring function

It saves High Peak value **h.PEV** or Low Peak value **L.PEV** against display value.

- •It can check in parameter group 0, the High Peak(**L.PEU**) value or the Low Peak(**L.PEU**) value will be continuously saved during checking.
- •Refer to Parameter group 0 for Reset.

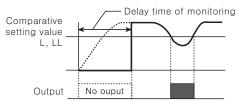
Monitoring delay function

It controls stably to limit L, LL output until certain output is displayed or all output until the equipment will be in a stable status against various change of input such as the staring current when the motor is running after power on.

1)Starting correction timer function

(**5***t***A***r*.*t* mode of Parameter group 1)

This function is to inhibit the output come for the setting time. (Time setting range 0.0 to 99.9sec.) Applicable output mode: S, H, L, B, I, F mode



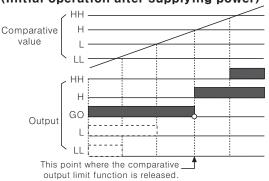
②Comparative output limit function

(F.dEFY mode of Parameter1 group)

This function is to limit the LL, L output before H or HH output.

Applicable output mode: S, B, F mode

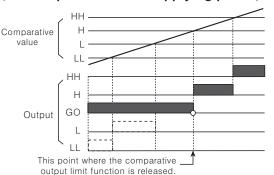
The output mode is S output mode (Initial operation after supplying power)



**Initial L, LL comparative output does not operate after supplying power.

*Eac setting value of HH, H, L, LL is not effected by each other. Therefore, HH value may be equal or lower than LL value.

●The output mode is B output mode (Initial operation after supplying power)



**Initial L, LL comparative output does not operate after supplying power.

**Each setting value of HH, H, L, LL effects on each other. Therefore, setting value should be LL<L<H<HH in sequence.

(A) Photo electric sensor

(B) Fiber optic sensor

> (C) Door/Area sensor

> (D) Proximity sensor

> (E) Pressure sensor

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

(J) Counter

(K) Timer

(L) Panel meter

M) Facho/ Speed/ Pulse neter

(N) Display

(O) Sensor controller

(P) Switching power supply

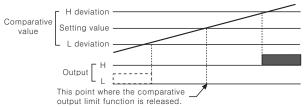
(Q) Stepping motor & Driver & Controller

(R) Graphic/ Logic panel

(S) Field network device

(T) Production stoppage models & replacement

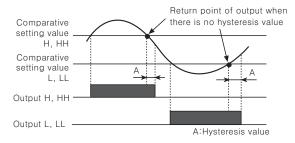
The output mode is F output mode (Initial operation after supplying power)



- *Initial L comparative output does not operate after supplying power.
- *The comparative output limit function will be released at the setting value (Standard setting).

OHysteresis function

Set the Hysteresis value (A) for comparative setting value in order to prevent unstable operation due to output is ON/OFF frequently.



DOT position	Setting range
00000	0000 to 9999
0.000	000.0 to 999.9
000.00	00.00 to 99.99
00.000	0.000 to 9.999
0.0000	0.000 to 0.999

- *It is able to set "0" but when set "0", the actual operation will be as "1".
- *The initial setting value is 0001.
- XIt is able to set in "hy5" mode of Parameter group 1.

OAuto-Zero time setting function

If there is no pulse input within setting time (Auto-zero time), it regards as the input signal is cut off then make the value as "00000" forcibly. Note that the Auto-zero time setting should be longer than the widest interval of input pulse. Otherwise it may be difficult to make the display value as "00000".

- •Auto-zero time setting range : 0.1 to 9999.9sec. (Factory default setting : 9999.9sec.)
- •When the display value is "00000", each output will respond to how it was programmed for "0".
- •Set the time in "Auto.A" and "Auto.b" mode of parameter group 1.

Be sure that some operation modes are not displayed. Please refer to M-13.

OLock setting function

This function is to set the enable or disable of each Parameter and mode changes.

Parameter	Parameter 0 group	Parameter 1 group	Parameter 2 group	Parameter 3 group
oFF	_	_	_	_
LoC O	•			
LoC I	_			
Lo[2	_	_	•	•
Lo[3	_	_	_	•

★ -: Unlock,

: Lock

*Lock setting is available in Parameter 3 group.

Olnner hardware Lock setting function

This function is to lock **Lol** in Parameter 3 group by Inner hardware Lock function in order to prevent wrong setting.

•MP5S, MP5Y, MP5W Series

	Pin	LoC mode	Remark
h0(Hardware Lock0)		Check: O, Change: O	Factory default
h1 (Hardware Lock1)		Check: O, Change: ×	
h2(Hardware Lock2)		Check:×, Change:×	

*Setting pin for Lock setting is located on internal PCB.

•MP5M Series

	SW	LoC mode
h0 (Hardware Lock0)	ON 2 OFF	Check:(), Change:()
h1 (Hardware Lock1)	ON 2 OFF	Check:○, Change:×
h2	1 2 ON I	Check:×, Change:×
(Hardware Lock2)	ON OFF	Shookers, Shangers

**It is possible to lock or unlock after supplied power in Inner hardware Lock setting.

OData bank switching function

This is a function to save comparative setting value and prescale value in each data bank (Data Bank 1, Data Bank 2) in order to make easy to use necessary data saved in each data bank.

- When terminal No.3 and 5 are open, comparative value and prescale value in Data Bank 1 will be activated.
- When terminal No.3 and 5 are shorted, comparative value and prescale value in Data Bank 2 will be activated.
- •How to save comparative value and prescale value in each Data Bank: Enter into parameter 2 group **P.bAnt** and select the Data Bank where you save the data. Then, save each comparative setting value and prescale value.
- *Data bank switching function is in MP5W series only.

M-25 Autonics

Time unit selection function

Enable to display PV value in various time ranges.

- •Time unit selection function can be set in parameter 2 group.
- •Applicable mode: Mode F3 to F6

SEC	MIN
999.99sec.	999.99min.
9999.9sec.	9999.9min.
99min59.9sec.	99hour59.9min.
9hour59min59sec.	999hour59min.
99999sec.	99999min.

- *There is no "dot" setting mode when select F3 to F6 operation mode.
- ** Time range of() part is not displayed in MP5M series.

Case detachment(DIP switch)

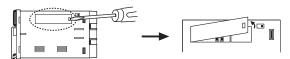
Please detach the case after turning off the power.

●MP5W Series/MP5Y Series/MP5S-4N



**Please press a pull of terminal ① and pull it toward ② direction.

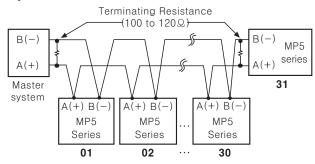
•MP5M Series



Pushing the Lock of DIP switch cover with a driver, squeeze and pull toward the outside, it detached. **Please be careful of the injury caused by tools.

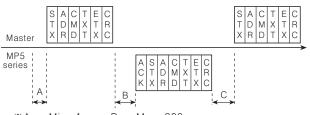
■Communication output

System structure



©Communication control ordering

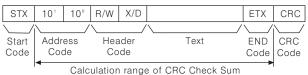
- 1. The communication control ordering of MP5 series is private protocol(Not compatible with other system).
- 2. After 4sec. being supplied the power into master system, then it starts to communicate.
- 3. Initial communication will be started by master system. When Command signal comes out from master system then MP5 series will response. If there is no response after 3times of the command signal from master system, error will be occurred.



 $A \rightarrow Min. 4sec., B \rightarrow Max. 300msec., C \rightarrow Min. 20msec.$

Communication command and block

Format of command and response



①Start code

It shows the first of BLOCK

 $STX \rightarrow [02H]$, in case of Response, ACK/NAK will be added.

②Address code

This code is master system can discern MP5 series and able to set within range of 01 to 99. (BCD ASCII)

3 Header code

It shows Command as 2 alphabets as below. RX(Read request) \rightarrow R[52H], X[58H] RD(Read response) \rightarrow R[52H], D[44H] WX(Write request) \rightarrow W[57H], X[58H] WD(Write response) \rightarrow W[57H], D[44H]

4)Text

It indicates the detail contents of Command /Response. (Refer to command item)

⑤END code

It indicates the end of BLOCK. ETX \rightarrow [03H]

©CRC

CRC is cyclic redundancy check and called polynominal code. CRC is for more reliable transmit/receive to check the error between transmitter and reciever.

There are CRC-8, CRC-16 and CRC-32, CRC-8 has been adopted in MP5 series according to CCITT-8 Polynomial regulation.

(Refer to CRC8 table) Result value is HEX 1 Byte.

< CRC8 Table >

	0	1	2	3	4	5	6	7	8	9	Α	В	С	D	Е	F
0	0x00	0x5E	0xBC	0xE2	0x61	0x3F	0xDD	0x83	0xC2	0x9C	0x7E	0x20	0xA3	0xFD	0x1F	0x41
1	0x9D	0xC3	0x21	0x7F	0xFC	0xA2	0x40	0x1E	0x5F	0x01	0xE3	0xBD	0x3E	0x60	0x82	0xDC
2	0x23	0x7D	0x9F	0xC1	0x42	0x1C	0xFE	0xA0	0xE1	0xBF	0x5D	0x03	0x80	0xDE	0x3C	0x62
3	0xBE	0xE0	0x02	0x5C	0xDF	0x81	0x63	0x3D	0x7C	0x22	0xC0	0x9E	0x1D	0x43	0xA1	0xFF
4	0x46	0x18	0xFA	0xA4	0x27	0x79	0x9B	0xC5	0x84	0xDA	0x38	0x66	0xE5	0xBB	0x59	0x07
5	0xDB	0x85	0x67	0x39	0xBA	0xE4	0x06	0x58	0x19	0x47	0xA5	0xFB	0x78	0x26	0xC4	0x9A
6	0x65	0x3B	0xD9	0x87	0x04	0x5A	0xB8	0xE6	0xA7	0xF9	0x1B	0x45	0xC6	0x98	0x7A	0x24
7	0xF8	0xA6	0x44	0x1A	0x99	0xC7	0x25	0x7B	0x3A	0x64	0x86	0xD8	0x5B	0x05	0xE7	0xB9
8	0x8C	0xD2	0x30	0x6E	0xED	0xB3	0x51	0x0F	0x4E	0x10	0xF2	0xAC	0x2F	0x71	0x93	0xCD
9	0x11	0x4F	0xAD	0xF3	0x70	0x2E	0xCC	0x92	0xD3	0x8D	0x6F	0x31	0xB2	0xEC	0x0E	0x50
Α	0xAF	0xF1	0x13	0x4D	0xCE	0x90	0x72	0x2C	0x6D	0x33	0xD1	0x8F	0x0C	0x52	0xB0	0xEE
В	0x32	0x6C	0x8E	0xD0	0x53	0x0D	0xEF	0xB1	0xF0	0xAE	0x4C	0x12	0x91	0xCF	0x2D	0x73
С	0xCA	0x94	0x76	0x28	0xAB	0xF5	0x17	0x49	0x08	0x56	0xB4	0xEA	0x69	0x37	0xD5	0x8B
D	0x57	0x09	0xEB	0xB5	0x36	0x68	0x8A	0xD4	0x95	0xCB	0x29	0x77	0xF4	0xAA	0x48	0x16
Е	0xE9	0xB7	0x55	0x0B	0x88	0xD6	0x34	0x6A	0x2B	0x75	0x97	0xC9	0x4A	0x14	0xF6	0xA8
F	0x74	0x2A	0xC8	0x96	0x15	0x4B	0xA9	0xF7	0xB6	0xE8	0x0A	0x54	0xD7	0x89	0x6B	0x35

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

(J) Counter

(K) Timer

(L) Panel meter

> M) acho/ peed/ ulse

(N) Display

(O) Sensor

(P) Switching power supply

(Q) Stepping motor & Driver & Controller

(R) Graphic/ Logic panel

(S) Field network device

(T) Production stoppage models & replacement

○Communication command

•The Charictaristic (Number) at " " is ASCII.

Sort	ACK	STX	Add	dr	Comr	nand	Bank	Со	de	+/-	10 ⁵	10 ⁴	10³	10²	10¹	10°	DP	ETX	CRC
Read	X	02			"R"	"X"					"0"	"0"	"0"	"0"	"0"	"0"	"0"	03	CRC
Read	06	02			"R"	"D"												03	CRC
Write	X	02			"W"	"X"												03	CRC
Write	06	02			"W"	"D"												03	CRC

Р	0	Process Value
С	0	Comparative Value HH
С	1	Comparative Value H
С	2	Comparative Value L
С	3	Comparative Value LL
Κ	0	Peak Value Max.
K	1	Peak Value Min.
Х	0	Prescaling Value X.Ain
Х	1	Prescaling Value X.Bin
Υ	0	Prescaling Value Y.Ain
Υ	1	Prescaling Value Y.Bin
R	0	Reset control of maximum/minimum values

•Read[RX] of measurement :

Address 01, Command RX

- 1. Command (Master)
 - (1)Command
 - ②Application: Address(01), Header code(RX), Process value(P0) of Bank(0), CRC Check sum(B5H)

STX	0	1	R	Χ	0	Р	0	+	0	0	0	0	0	0	0	ETX	CRC
Start	Add	Iress	Comr	mand	Bank	Comi	mand	Symbol	10 ⁵	10 ⁴	10³	10²	10¹	10°	Decimal point	END	Check sum
02	30	31	52	58	30	50	30	2B	30	30	30	30	30	30	30	03	B5

- 2. Response
 - ①Normal receive: Adding ACK [06H] to current value of Data transmission Bank (0) is +1.234.

ACK	STX	0	1	R	D	0	Р	0	+	0	0	1	2	3	4	3	ETX	CRC
ACK	Start	Add	ress	Comi	mand	Bank	Comr	mand	Symbol	10 ⁵	10 ⁴	10³	10²	10¹	10°	Dec- imal point	Ena	Check sum
06	02	30	31	52	44	30	50	30	2B	30	30	31	32	33	34	33	03	23

②Normal receive: Adding ACK[06H] to current value of Data transmission Bank(0) is -156.7.

ACK	STX	0	1	R	D	0	Р	0	-	0	0	1	5	6	7	1	ETX	CRC
ACK	Start	Add	ress	Comi	mand	Bank	Com	mand	Symbol	10 ⁵	10 ⁴	10³	10²	10¹	10°	Dec- imal point	End	Check sum
06	02	30	31	52	44	30	50	30	2D	30	30	31	35	36	37	31	03	75

•Write[WX] of measurement / setting value :

Address 01, Command WX

- 1. COMMAND (Master)
 - **①Command**
 - ②Application: Address(01), Head Code(WX),

The setting value into SV-HH (CO) of BANK(0) is +1.234.

STX	0	1	W	Χ	0	С	0	+	0	0	1	2	3	4	3	ETX	CRC
Start	Add	ress	Comr	mand	Bank	Comi	mand	Symbol	10 ⁵	10 ⁴	10 ³	10²	10¹	10°	Dec- imal point	End	Check sum
02	30	31	57	58	30	43	30	2B	30	30	31	32	33	34	33	03	5D

2. Response (MP5 Series)

When completing the operation after normal receive.

ACK	STX	0	1	W	D	0	С	0	+	0	0	1	2	3	4	3	ETX	CRC
ACK	Start	Address		Command		Bank	Command		Symbol	10 ⁵	10 ⁴	10³	10²	10¹	10°	Dec- imal point	End	Check sum
06	02	30	31	57	44	30	43	30	2B	30	30	31	32	33	34	35	03	3С

3. CRC error: Transmit NAK[15H] only.

(Need to transmit again)

- 4. Other: No response of ACK/NAK
 - ①After receiving STX, the address are not the same.
 - ②When receive buffer is overflown.
 - 3When the baud rate or other communication setting value are not the same.
- 5. If there is no response of ACK/NAK
 - ①Check the status of lines
 - ②Check the communication condition (Setting value)
 - 3When the problem is occurred due to noise, try to operate communication 3 times more until recovery
 - When communication is failed frequently, please adjust the communication speed.

■Precaution for communicating with MP5 series

- It is not possible to modify Parameter (Baud rate, Address etc) related to communication of MP5 series on line with high order systems such as PC, PLC etc. (Error will be occurred)
- 2. Firstly make communication Parameter of MP5 series and high order system at one.
- 3. It is not allow to set overlapping communication number at the same communication line.

 (Error will be occurred)
- Please use Twist pair wire for RS485 communication.
- 5. Communication cable can be extended up to 800m, and maximum 31 equipments can be connected
- 6. When connect communication cable between MP5 series and high order system, the vertical resistance (100 to 200Ω) must be installed at between both communication lines.
- 7. Please check Parameter related to communication

①Start bit : 1bit(Fix)
②Stop bit : 1bit(Fix)
③Parity bit : Non(Fix)
④Data bit : 8bit(Fix)

⑤Baud rate: 2400, 4800, 9600 (Set possibility)

⑥Address : 01 to 99(Set possibility)

M-27 Autonics